

Monitoring Forest Disturbance and Structure in the Northeast with Sensor Fusion to Support Ecosystem Assessment

Lamprey River Symposium

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1. AGS Missions
2. Project Goals
3. Field Data Collection Sites
4. Example Remote Sensing Observations
5. Lidar Basics & Tools
6. Lidar Products
7. Conclusions & Next Steps

Leading edge science-based firm, established in 2000

- Monitoring, assessing, developing
 - geospatial decisions support systems
 - environmental change and ecosystem services
 - create/apply tools and web mapping for non-experts
- National and international collaborators
 - academic institutions, government agencies, industries, and private clients
- This project partners with UNH & UMASS

Forest Disturbances



NH Tornado, 2008



Gypsy Moths, RI



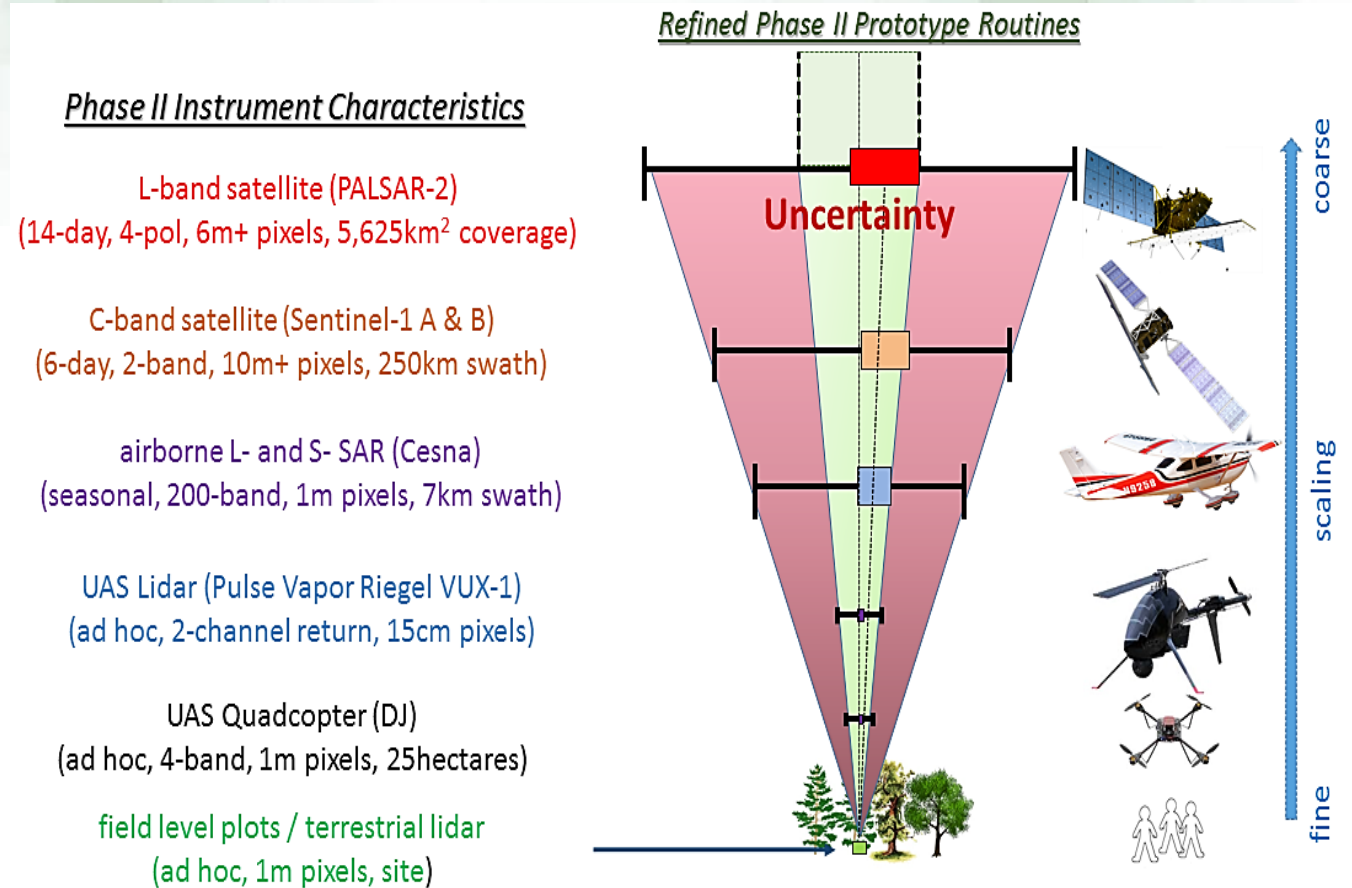
WMNF Fire, 2017



NH land conversion to cattle farm in Epsom, NH



- Map forest structure metrics
 - Aboveground biomass, forest stand height, crown canopy cover
- Understand relationships between metrics, ecosystem functions and services, and their dynamics
- Detect and evaluate intensity, frequency and magnitude of disturbances



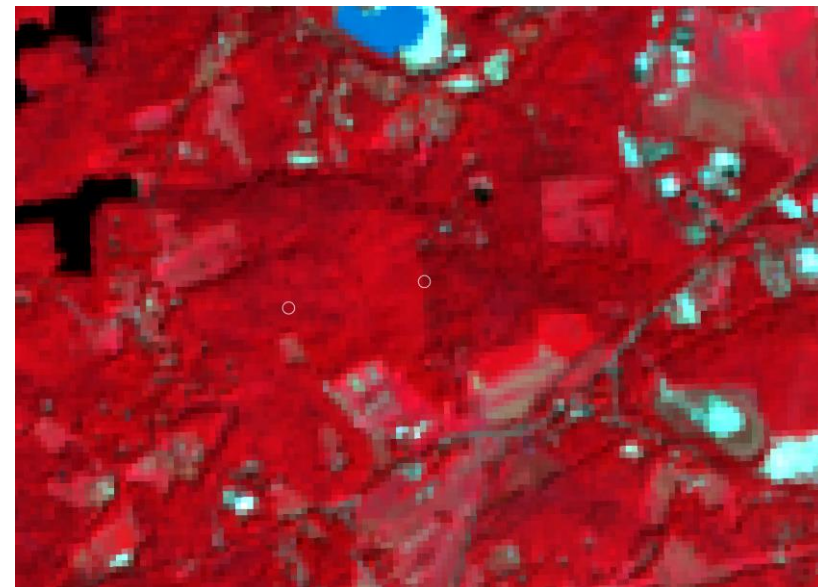
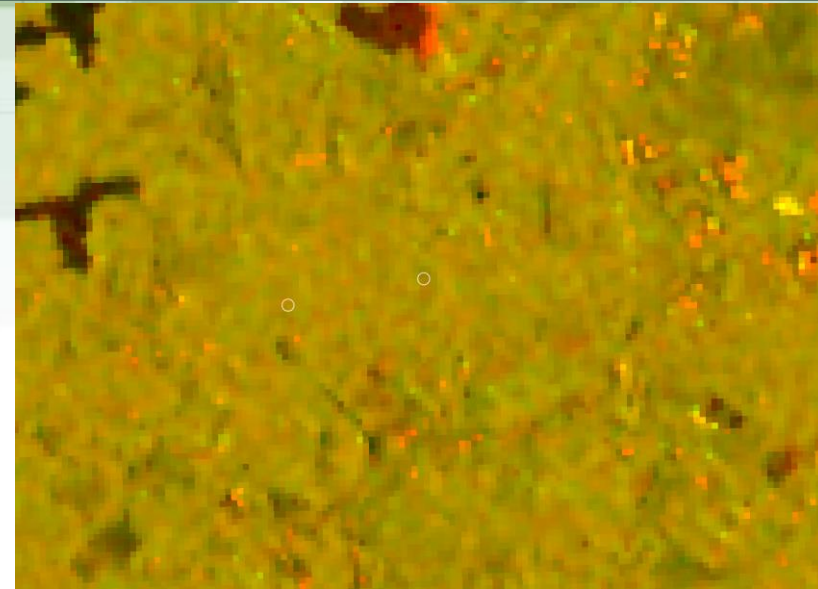
Field Work at a Lamprey / Oyster River Watershed Site



Satellite Sensor Data over Lamprey River Watershed Region

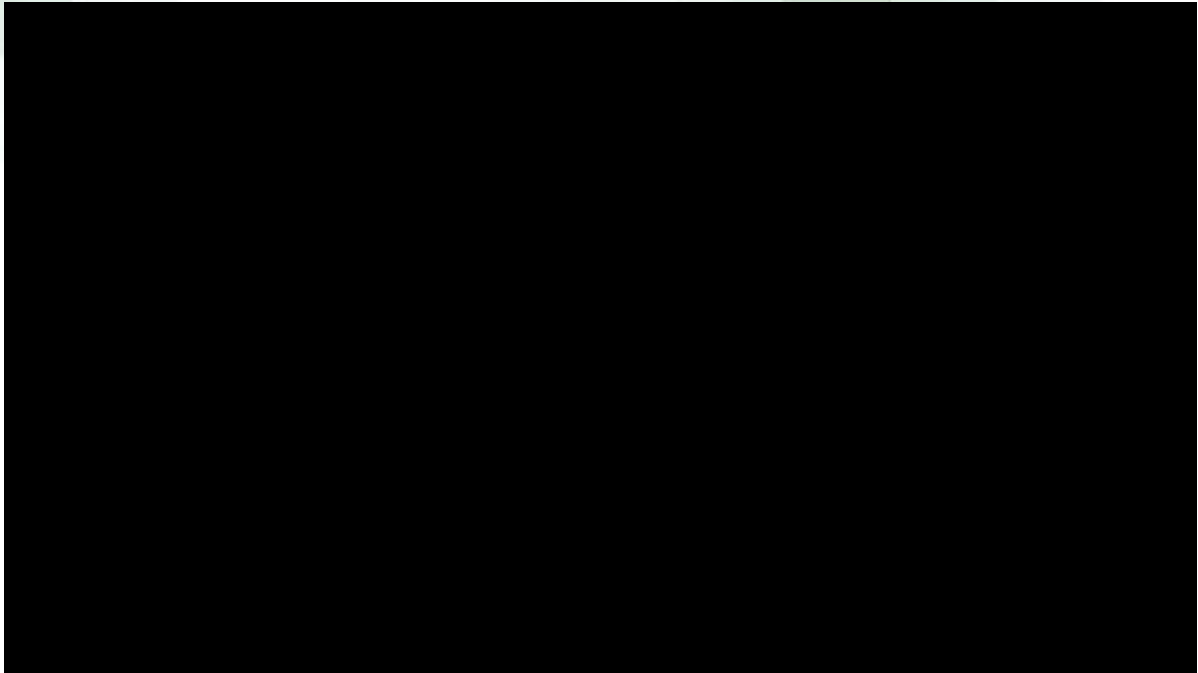
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- Radar (L-band PALSAR-2, C-Band Sentinel-1A):
 - Active sensor
 - through cloud cover
 - vegetation structure, geometry, and moisture content
 - wavelength frequency, polarization and viewing geometry
 - longer wavelengths (smaller frequency) = greater penetration of canopy
 - cross-pol (HV) or dual-pol (HH or VV)
 - incidence angle (θ)
- Optical (Landsat 8)
 - Passive sensor
 - susceptible to interference from clouds and other climate factors
 - Cloudmask
 - include the visible, near-, middle-, and shortwave-infrared
 - detecting and measuring forest health



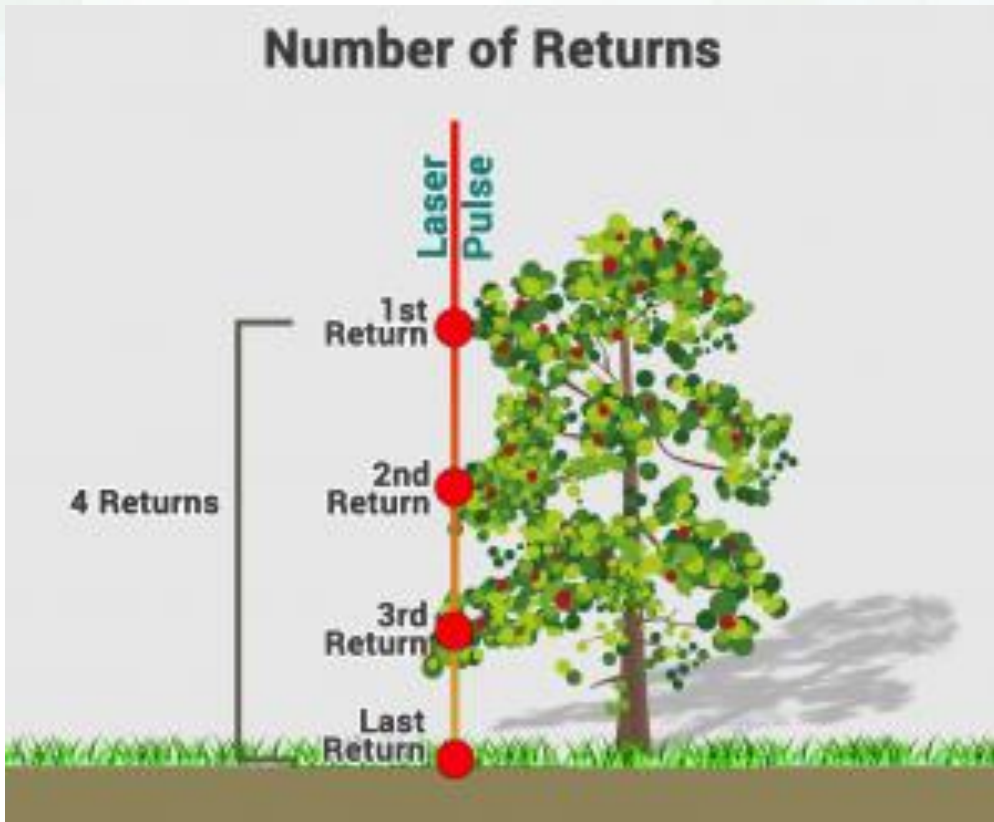
Components of a Lidar System

- Laser device
- inertial navigational measurement unit (IMU)
 - continuously records aircraft's orientation
- High-precision airborne global positioning system (GPS) unit
- computer interface
 - manages communication among devices and stores data
- GPS base station
 - known location on the ground
 - within 50 km of the aircraft



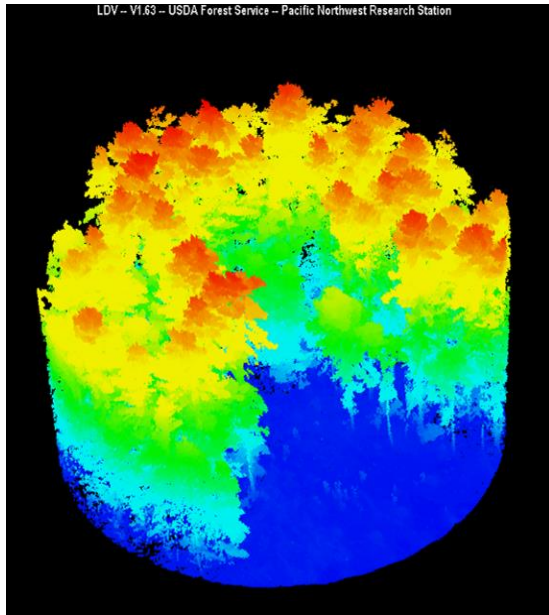
- Laser device emits pulses of light
 - determines the range to a target
- Distance to target = time delay between the emission of the pulse and the detection of the reflected (backscattered) signal
- Pulses in the near-infrared part of the spectrum (1040 - 1065 nm)
 - topographic mapping and forestry applications
- Often cost-prohibitive
 - Very high spatial resolution
 - Expensive equipment
 - not easy to collect (need pilot, someone knowledgeable about sensor systems)

Number of Returns

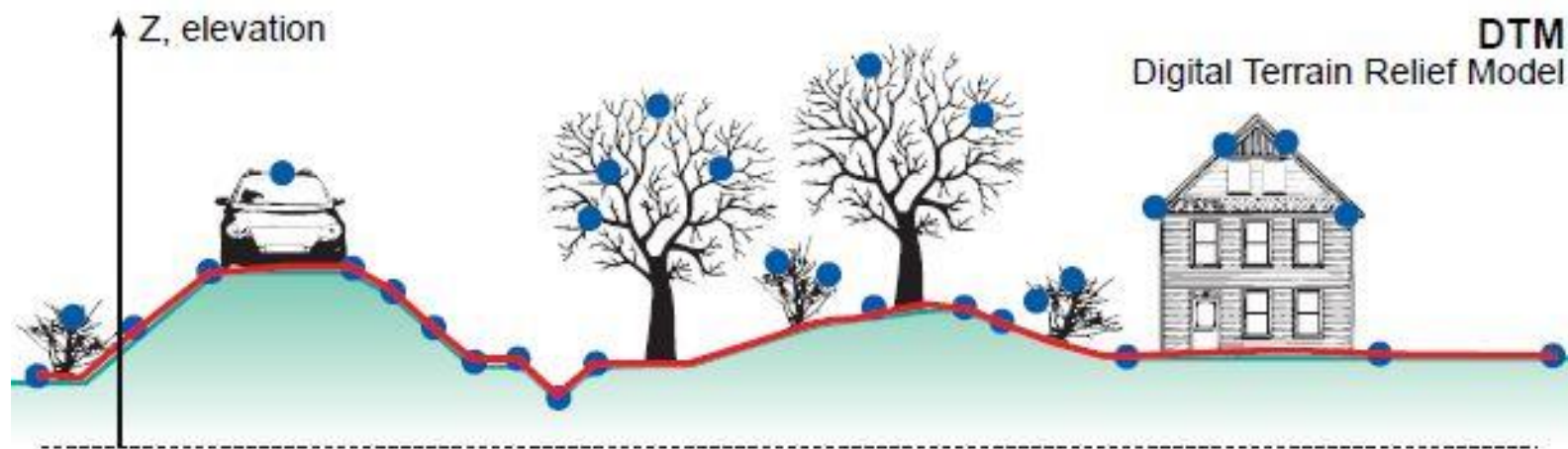
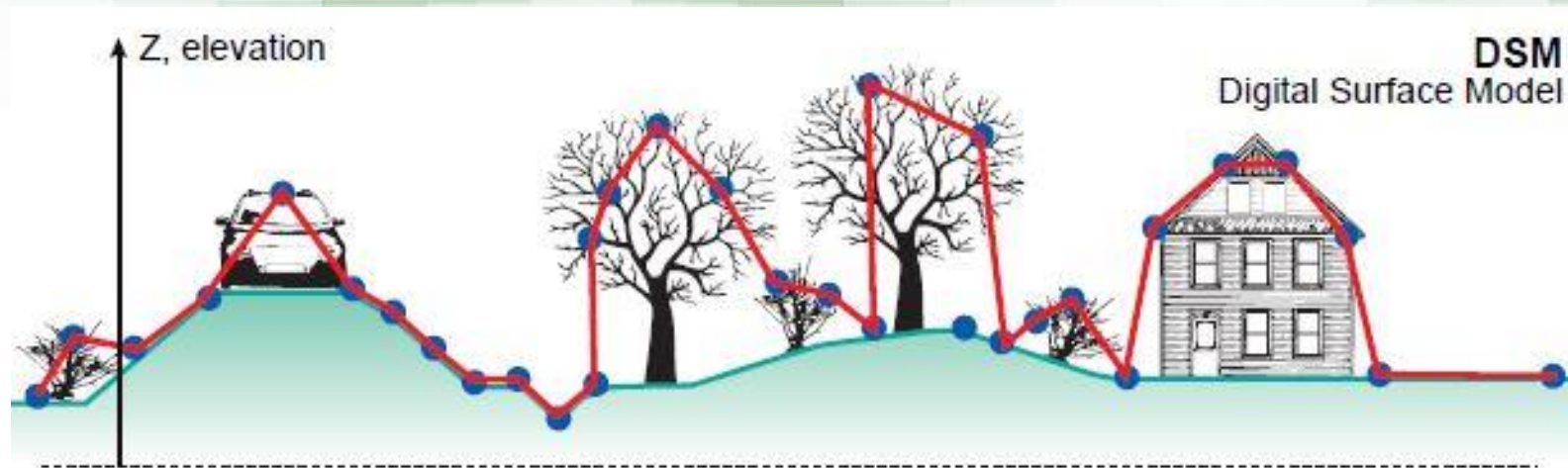


- Pulse density = spatial resolution
- Return density = mean number of returns in the data set in a unit square area
- Return intensity
 - strength of the beam backscattering
 - Depends on target reflectance properties
 - Can be used in classification
- Return number = rank of a return among those generated from a single beam
- Number of returns
- Classification scheme (2=ground,3=low vegetation, 4=medium vegetation, etc...)

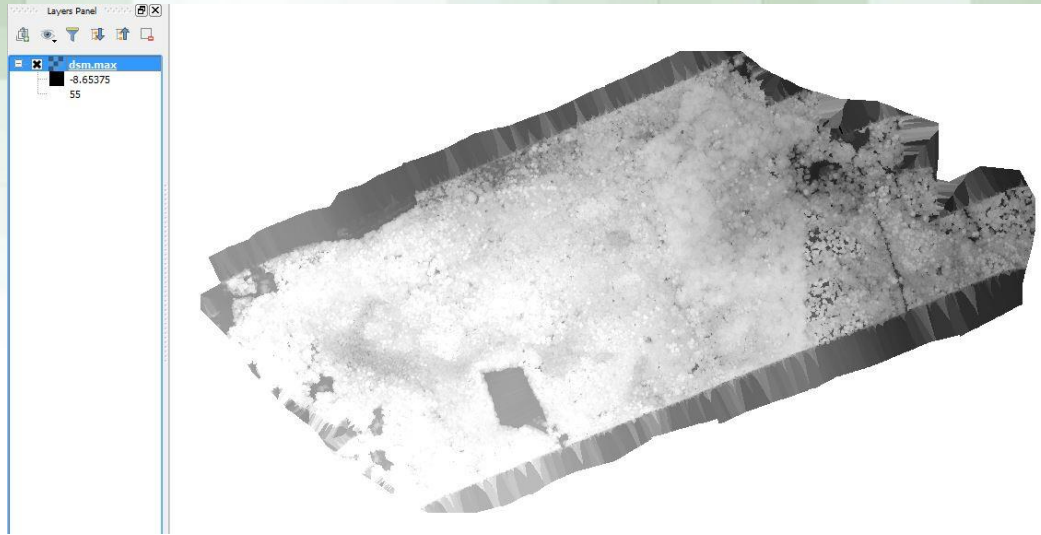
LAS files- (Lidar Data Exchange File, binary)



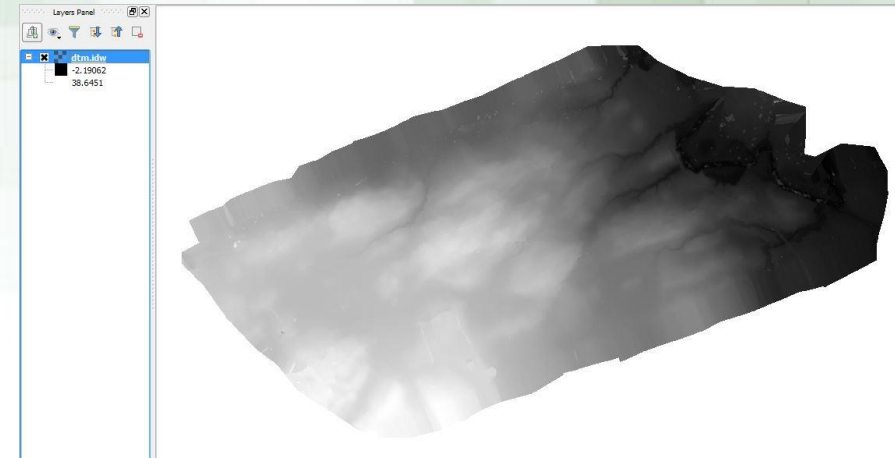
- Lidar2dems
 - Create DEMs from Lidar data, uses PDAL
 - Locally developed tool, AGS/UNH/outside developers
- FUSION
 - Generate point cloud statistics, canopy cover stats, select/display Lidar data
 - developed by the Silviculture and Forest Models Team, Research Branch of the US Forest Service
- PDAL (Point Data Abstraction Library)
 - translates and processes point cloud data
- LAStools
 - classify, tile, convert, filter, raster, triangulate, contour, clip, and polygonize LiDAR data



Lidar Products, etc...

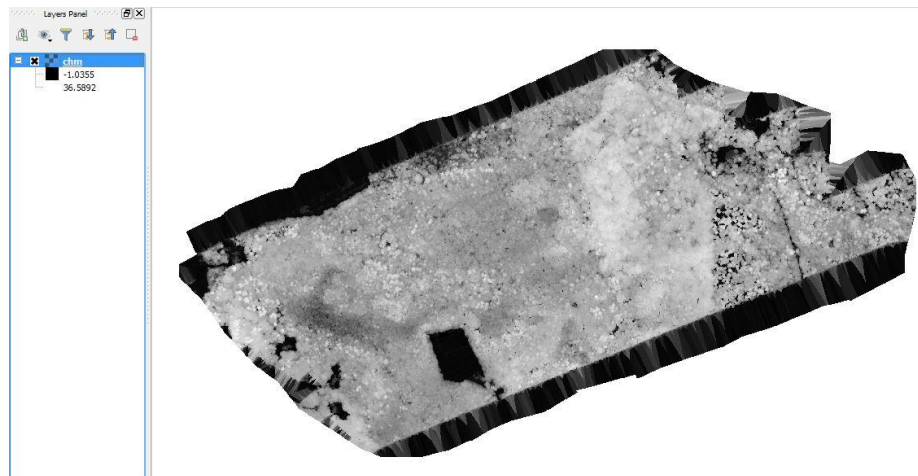


DSM

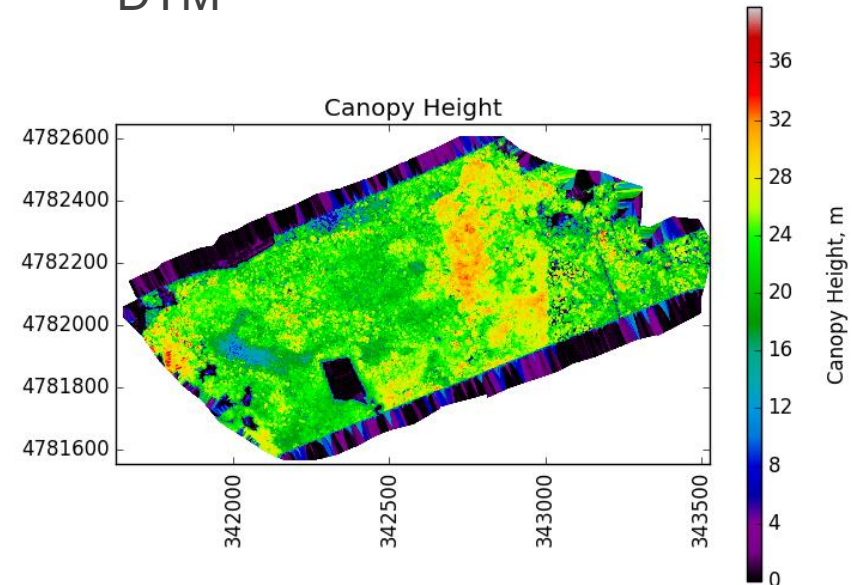


DTM

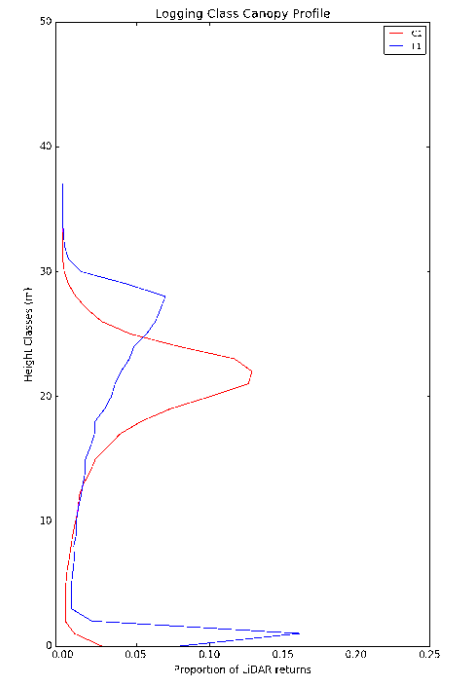
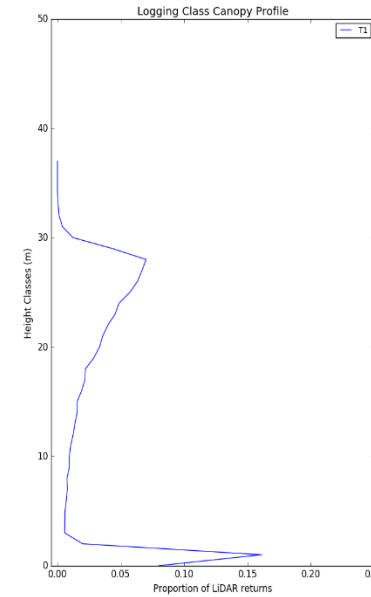
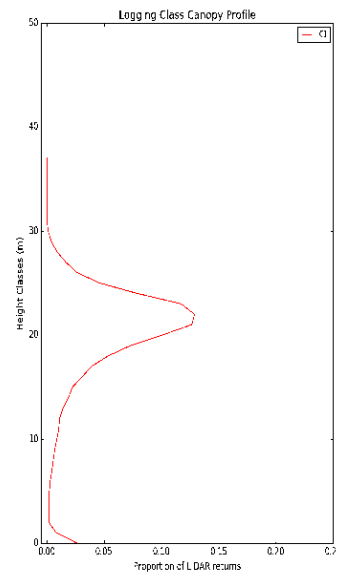
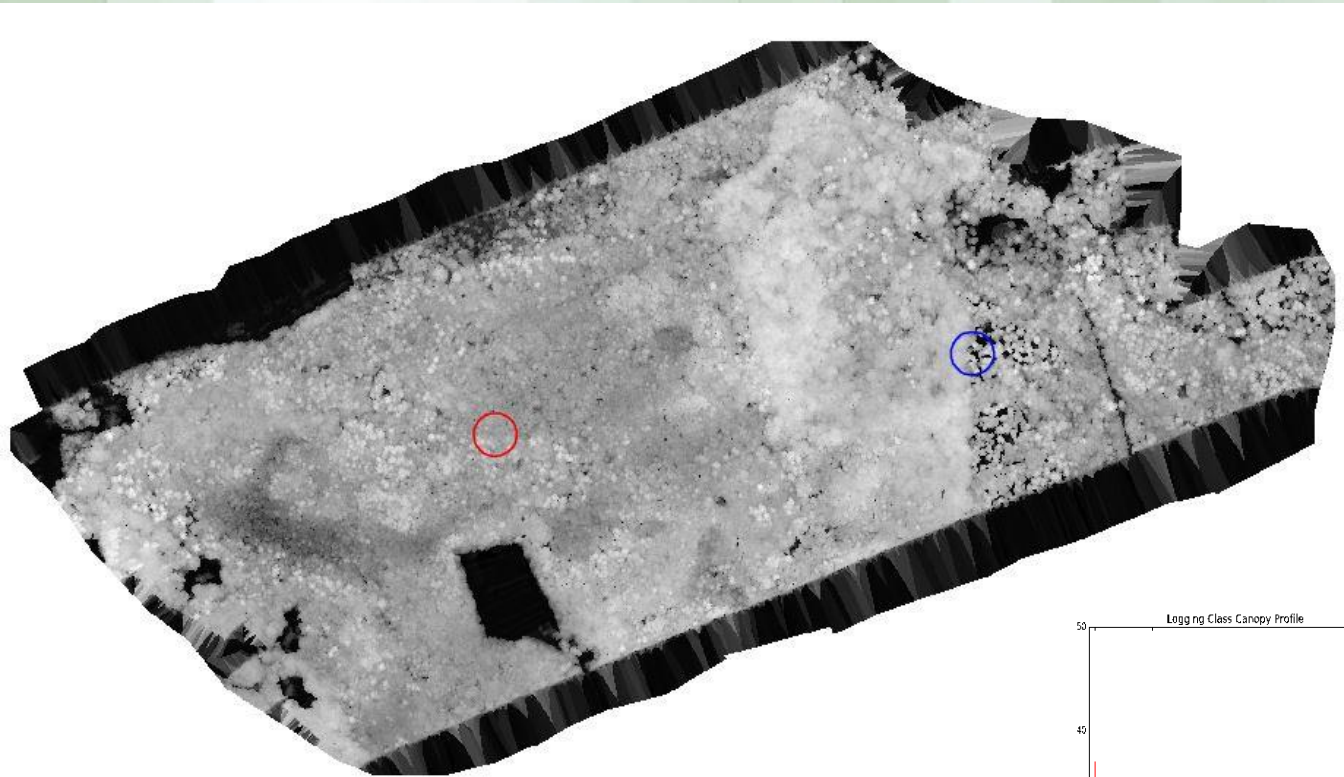
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CHM



Field Data Collection Sites- Kingman Farm



- Multi-sensor fusion / combination provides more thorough assessment
- Lidar very accurate tree height maps @ 1m resolution
- Repeat-pass InSAR fairly accurate height maps @ ~1-3 hectare scale

Next Steps

- Measuring tornado regrowth and shifts in forest structure (stand height, AGB, crown size)
- Gypsy Moth monitoring and forecasting this upcoming season (defoliation extent, intensity, timing)
- Other application partnerships in Lamprey watershed?

Questions?

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Thank you!

Happy to share products, code, and field data!

NEON. “How Does LiDAR Remote Sensing Work? Light Detection and Ranging”. YouTube. YouTube, 24 November 2014. Web. 5 Jan 2017.

[Photograph of RI Gypsy Moth Aerial]. Retrieved from <https://www.bostonglobe.com/metro/2016/06/29/the-gypsy-moth-effect/l4dEU5x6LCrBrdFV9Kz9EP/story.html?pic=9> (Page4)

[Photograph of DSM versus DTM]. Retrieved from <http://www.charim.net/datamanagement/32> (Page 12).

[Photograph of White Mountain Regional Forest Fire]. Retrieved from <http://nhpr.org/post/rain-helping-firefighters-battle-white-mountains#stream/0> (Page 4).

[Photograph of 2008 New Hampshire Tornado]. Retrieved from <https://www.adamdow.com/blog/posts/2008/07/29/tornado-pictures/> (Page 4).

[Photograph of New Hampshire Forest Clearing for Cattle Farm]. Retrieved from <http://nhforestry.com/land-clearings/> (Page 4).

[Photograph of Lidar Returns from Vegetation]. Retrieved from <http://gisgeography.com/lidar-light-detection-and-ranging/> (Page 9).

Torbick, Nathan. [Photographer] (2017). *Forest Data Field Collection* [Photograph] (Page 14).